

6. S896 - Algorithmic Statistics

Lecture 3: Introduction to Graphical Models

So far: product measures are nice (independence)
gaussians are nice (tails)
general dist'ns aren't nice (exponential
sample lower
bounds for
easy tasks
e.g. testing
uniformity)

Today: exploit conditional independence structure

Let us revisit multi-dimensional gaussians

$$p(x_1, \dots, x_n) = \frac{1}{(2\pi)^{n/2} |\Sigma|} \cdot \exp\left(-\frac{1}{2} x^T \Sigma^{-1} x\right) \quad \text{density of } N(\mu, \Sigma)$$

Σ : covariance matrix $P = \Sigma^{-1}$: precision matrix

↳ term used
by Gauss

$G = (V, E)$ where $V = \{1, \dots, n\}$

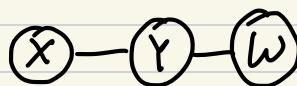
& $(i, j) \in E$ iff $P_{ij} \neq 0$

Eg. suppose $Z_1, Z_2, Z_3 \stackrel{\text{iid}}{\sim} N(0, 1)$

$$X = Z_1, Y = Z_1 + Z_2, W = Z_1 + Z_2 + Z_3$$

$$\Sigma = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix} \Rightarrow \Sigma^{-1} = \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix}$$

→ resulting graph



X_i & X_j are conditionally independent given $X_{[n] \setminus \{i,j\}}$

Claim: ① For $i \neq j$ suppose i, j in G . Then: $X_i \perp\!\!\!\perp X_j \mid X_{[n] \setminus \{i,j\}}$

② For disjoint sets A, B, S suppose all paths from A to B in G go through S - written $A \perp\!\!\!\perp B \mid S$

Then $X_A \perp\!\!\!\perp X_B \mid X_S$

Proof: ① denote $S = [n] \setminus \{i,j\}$

$$p(x) \propto \exp \left(-\frac{1}{2} P_{ii} x_i^2 - \frac{1}{2} P_{jj} x_j^2 - x_i P_{iS} x_S - x_j P_{jS} x_S - \frac{1}{2} x_S^\top P_{SS} x_S \right)$$

so for some functions f, g : $p(x) = f(x_i, x_S) \cdot g(x_j, x_S)$
 $\Rightarrow X_i \perp\!\!\!\perp X_j \mid X_S$

② similar

Lemma 1

Conditional Independence Cheat Sheet

[Whatever I say holds for discrete r.v.'s & their pmf's p(.) or continuous r.v.'s w/ densities p(.)]

Def 1: The conditional density of X given Y is any f'n $p(x|y)$ such that

$$p(x,y) = p(y) \cdot p(x|y)$$

Def 2: Let X, Y, Z be r.v.'s. We say that X & Y are conditionally independent given Z if

$$p(x|y,z) = p(x|z) \quad \forall x, y, z \text{ s.t. } p(y,z) > 0$$

In this case we write $X \perp\!\!\!\perp Y | Z$

Lemma 1: Let X, Y, Z be random variables. Then the following are equivalent:

(a) $p(x,y,z) = f(x,z) \cdot g(y,z)$ for some f'ns f, g & all values x, y, z

(b) $p(x|y,z) = p(x|z) \quad \forall x, y, z \text{ s.t. } p(y,z) > 0$
(i.e. $X \perp\!\!\!\perp Y | Z$)

Proof: (a \Rightarrow b) $p(y,z) = \int_x p(x,y,z) dx = \int_x f(x,z) g(y,z) dx$
 $= g(y,z) \cdot \tilde{f}(z)$

Suppose y, z s.t. $p(y, z) > 0 \Rightarrow \tilde{f}(z) > 0 \Rightarrow g(y, z) = \frac{p(y, z)}{\tilde{f}(z)}$

$$\stackrel{\textcircled{b}}{\Rightarrow} p(x, y, z) = p(y, z) \cdot \underbrace{\frac{f(x, z)}{\tilde{f}(z)}}_{\text{||| by definition}} p(x|yz)$$

$\Rightarrow p(x|yz)$ does not depend on y

$$\Rightarrow p(x|yz) = p(x|z) \Rightarrow \textcircled{a}$$

↳ why?

$$\text{well... } p(xyz) = p(yz) \cdot p(x|yz)$$

$$\underbrace{\int p(xyz) dy}_{\text{|||}} = \underbrace{\int p(yz) p(x|yz) dy}_{\text{|||}} p(z)$$

$$p(xz)$$

$$\underbrace{p(x|yz)}_{\text{|||}} p(z)$$

$$p(x|z) \text{ by def.}$$

$$\left(\textcircled{b} \Rightarrow \textcircled{a} \right) p(xyz) = p(yz) p(x|yz) \stackrel{\textcircled{a}}{=} p(yz) p(x|z)$$

☒

Remark: Seems like we have been fooling around w/
symbols. But cond. independence non-trivial!

e.g. for r.v.'s X, Y, Z

$$X \perp\!\!\!\perp Y \not\Rightarrow X \perp\!\!\!\perp Y | Z$$

$$X \perp\!\!\!\perp Y | Z \not\Rightarrow X \perp\!\!\!\perp Y$$

} think of examples!

Lemma 2: The following are true for r.v.'s X, Y, Z, W

$$1. X \perp\!\!\!\perp Y, W | Z \Rightarrow X \perp\!\!\!\perp Y | Z \quad \text{"decomposition"}$$

$$2. X \perp\!\!\!\perp Y, W | Z \Rightarrow X \perp\!\!\!\perp W | Y, Z \quad \text{"weak union"}$$

$$3. \begin{array}{l} X \perp\!\!\!\perp W | Y, Z \\ X \perp\!\!\!\perp Y | Z \end{array} \left. \right\} \Rightarrow X \perp\!\!\!\perp Y, W | Z \quad \text{"contraction"}$$

$$4. \text{If } p(x, y, w, z) > 0, \forall x, y, w, z, \text{ then} \quad \text{"intersection"}$$

$$X \perp\!\!\!\perp W | Y, Z \& X \perp\!\!\!\perp Y | W, Z \Rightarrow X \perp\!\!\!\perp W Y | Z$$

Proof:

- $p(x, y, w | z) = p(x | z) \cdot p(y, w | z) \xrightarrow{\int_w} p(x, y | z) = p(x | z) \cdot p(y | z)$
- $p(x, y, w | z) = p(x | z) \cdot p(y, w | z) = \underbrace{p(x | z) \cdot p(y | z)}_{\text{II (use I)}} \cdot p(w | y, z)$

$$\text{thus } p(w | y, z) \equiv p(w | y, x, z) \left(\text{by definition I} \right) \textcircled{*}$$

$$\text{So } p(x, w | y, z) = p(x | y, z) \cdot \underbrace{p(w | x, y, z)}_{\substack{\text{II} \textcircled{*} \\ p(w | y, z)}}$$

$$3. \ p(x, y, w | z) = p(y|z) p(xw|y, z)$$

$$p(x, w | y, z) = \underbrace{p(x | y, z)}_{p(x | z)} p(w | y, z)$$

4. Use Lemma 1

$$p(x, y, w, z) = f(x, y, z) \cdot g(w, y, z), \text{ for some } f, g$$

$$= \tilde{f}(x, w, z) \cdot \tilde{g}(y, w, z), \text{ for some } \tilde{f}, \tilde{g}$$

by positivity \Rightarrow

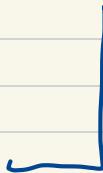
$$f(x, y, z) = \frac{\tilde{f}(x, w, z) \tilde{g}(y, w, z)}{g(w, y, z)}$$

$$= \frac{\tilde{f}(x, w_0, z) \tilde{g}(y, w_0, z)}{g(w_0, y, z)} \quad \begin{matrix} \text{for any} \\ \text{fixed } w_0 \\ \text{since LHS} \\ \text{doesn't} \\ \text{depend on } z \end{matrix}$$

thus $f(x, y, z) = \hat{f}(x, z) \hat{g}(y, z)$

$$\Rightarrow p(x, y, w, z) = \hat{f}(x, z) \hat{g}(y, z) g(w, y, z)$$

$\Rightarrow x \perp\!\!\!\perp y w | z$



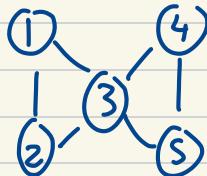
Undirected graphical Models

Recall: In multivariate Gaussians structure of precision matrix implied cond. independence properties of the dist'n generalize?

Def 3: given undirected graph $G = (V, E)$, a probability dist'n $p(x_v)$ satisfies the pairwise Markov property of G iff

$$(i, j) \notin E \Rightarrow X_i \perp\!\!\!\perp X_j \mid X_{V \setminus \{i, j\}}$$

e.g.



$$X_1 \perp\!\!\!\perp X_4 \mid X_{2,3,5}$$

$$X_2 \perp\!\!\!\perp X_5 \mid X_{1,3,4}$$

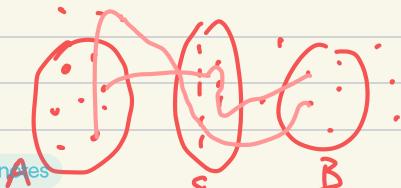
$$X_2 \perp\!\!\!\perp X_4 \mid X_{1,3,5}$$

$$X_1 \perp\!\!\!\perp X_5 \mid X_{2,3,4}$$

Def 4: given G , dist'n p satisfies the global Markov property of G iff

for all disjoint sets $A, B, S \subseteq V$:

if $A \perp\!\!\!\perp B \mid S$ (i.e. $A \& B$ disconnected in $G \mid S$)



then $X_A \perp\!\!\!\perp X_B \mid X_S$

e.g. in above graph $X_{12} \perp\!\!\!\perp X_5 | X_3$

Def 5: Given G , we say p factorizes according to G iff

$$p(x_v) = \prod_{C \in C(G)} \underbrace{\psi_c(x_c)}_{\text{cliques of } G} \xrightarrow{\text{some function}} \text{called clique } c \text{ potential}$$

Theorem: If $p(x_v)$ factorizes according to G , then p satisfies global Markov property wrt G .
(& thus also local Markov property)

Proof: take disjoint $A, B, S \subseteq V$ such that $\underbrace{A \perp\!\!\!\perp B | S}_{A \text{ & } B \text{ are disconnected in } G|S}$

\tilde{A} : vertices connected to A via paths in $G|S$

$$\tilde{B} = V \setminus (\tilde{S} \cup \tilde{A})$$

$$\text{Clearly } A \subseteq \tilde{A}, B \subseteq \tilde{B}$$

also every clique C is either $C \subseteq \tilde{A} \leftarrow$
or $C \subseteq \tilde{B} \leftarrow \leftarrow \subseteq$

$$\text{thus } p(x) = \prod_{c \in C} \psi_c(x_c) = \prod_{c \in C_A} \psi_c(x_c) \cdot \prod_{c \in C_B} \psi_c(x_c)$$

$$= f(x_{\tilde{A}}, x_s) \cdot f(x_{\tilde{B}}, x_s)$$

Lemma 1

$$\Rightarrow X_{\tilde{A}} \perp\!\!\!\perp X_{\tilde{B}} \mid X_s$$

Lemma 2

$$\Rightarrow X_A \perp\!\!\!\perp X_B \mid X_s$$



p obeys
 p factorizes wrt $G \Rightarrow$ global Markov property
wrt G

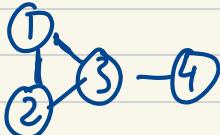
↑
how about -- this? Can we close the circle?
↓
 p obeys local Markov property wrt G

Theorem [Hammersley - Clifford '71]

If $p(x_v) > 0, \forall x_v$, and p obeys local Markov property wrt. graph $G = (V, E)$, then p factorizes wrt G !

Remark: Conditions in H-C theorem are necessary!

Consider graph G :



suppose X_3, X_4 are ind. Bernoulli($\frac{1}{2}$)

and $X_1 = X_2 = X_4$ wrt 1

then $X_1 \perp\!\!\!\perp X_4 | X_2, X_3$

$X_2 \perp\!\!\!\perp X_4 | X_1, X_3$

But $X_4 \perp\!\!\!\perp X_1, X_2 | X_3$ (so p can't factorize wrt 6
as otherwise this would also be implied)

Nomenclature: A prob. dist'n that factorizes wrt G
is called

a Markov Random Field

a Markov Network

an undirected graphical model

When $p(x_v) > 0$ it's also called a

Gibbs Random Field

E.g. Applications of Undirected Graphical Models

- Used a ton in Statistical Physics
Probability
Machine Learning
Statistics
Social Science
Biology
:

- commonly, they are described in term of
 - an undirected graph: $G = (V, E)$
 - an energy function: $E(x_v)$
 - a temperature parameter: T

with respect to which: $p(x_v) = \frac{1}{Z} \exp\left(-\frac{1}{T} \cdot E(x_v)\right)$

↖ called "partition function"
[hard to appx in general]

Example 1: Ising Model

$$x_v \in \{\pm 1\}^V$$

$$p(x_v) = \frac{1}{Z} \exp\left(\sum_{i,j} \theta_{ij} x_i x_j + \sum_i \theta_i x_i\right)$$

direct interaction between i, j external field on i

ex 2: ERGMs (exponential family random graph models)

- dist'n over graph (a.k.a. adjacency matrices)
- $V = [n] \times [n]$

$$x_v \in \{0, 1\}^{[n] \times [n]}$$

$\hookrightarrow x_{ij} \in \{0, 1\}$ depending on whether node i & j are connected

$$p(x_v) \propto \exp \left(\sum_{S \in M} b_S \cdot \left(\begin{array}{l} \text{\# copies of } S \\ \text{in graph} \\ \text{defined by } x_v \end{array} \right) \right)$$

some family
of small
graphs e.g. $M = \{-\circlearrowleft, \Delta, V, \square\}$

Closing Fun: recall testing if a dist'n q over $\{\pm 1\}^n$ is uniform i.e.

(P): $q = U(\{\pm 1\}^n)$ vs $d_{TV}(q, U) > \varepsilon$
requires $\sqrt{\frac{2^n}{\varepsilon^2}}$ samples

What if I know that q is nice, eg.
suppose I know q is an Ising model

$$q(x) = \frac{1}{Z} \exp\left(\sum_{ij} \theta_{ij} x_i x_j + \sum_i \theta_i x_i\right)$$

with unknown θ_{ij} 's ?

Claim: If q is Ising model \nearrow whose $|\theta|_2 \leq O(1)$ can solve
problem P w/ $\text{poly}(n, \frac{1}{\epsilon})$ samples.

[Dashkali]-
Dikhala-
Kamath'19]

Proof Idea: take two Ising models θ, θ'

$$\text{SKL}(q_\theta, q_{\theta'}) = \text{KL}(q_\theta || q_{\theta'}) + \text{KL}(q_{\theta'} || q_\theta)$$

$$= \sum_x q_\theta \log \frac{q_\theta}{q_{\theta'}} + \sum_x q_{\theta'} \log \frac{q_{\theta'}}{q_\theta}$$

$$= \sum_x q_\theta(x) \log \frac{\frac{1}{z_\theta} \exp(-)}{\frac{1}{z_{\theta'}} \exp(-)} + \sum_x q_{\theta'}(x) \log \frac{\frac{1}{z_{\theta'}} \exp(-)}{\frac{1}{z_\theta} \exp(-)}$$

$$\begin{aligned}
 &= \sum_x q_{\theta}(x) \left(\sum_{i,j} (\theta_{ij} - \theta'_{ij}) x_i x_j + \sum_i (\theta_i - \theta'_i) x_i \right) \\
 &\quad \text{cancel } \log \frac{z_{\theta}}{z_{\theta'}} \text{ w/ } \log \frac{z_{\theta'}}{z_{\theta}} \\
 &+ \sum_x q_{\theta'}(x) \left(\sum_{i,j} (\theta'_{ij} - \theta_{ij}) x_i x_j + \sum_i (\theta'_i - \theta_i) x_i \right) \\
 &= \sum_{i,j} (\theta_{ij} - \theta'_{ij}) \cdot \left(\mathbb{E}_{\theta} x_i x_j - \mathbb{E}_{\theta'} x_i x_j \right) \\
 &+ \sum_i (\theta_i - \theta'_i) \left(\mathbb{E}_{\theta} x_i - \mathbb{E}_{\theta'} x_i \right)
 \end{aligned}$$

now take $\theta' = \vec{\theta}$ then $q_{\theta'} = \text{uniform dist'n}$

$$SKL(P_{\theta}, \text{Uniform}) = \sum_{ij} \theta_{ij} \cdot \mathbb{E}_{\theta} x_i x_j + \sum_i \theta_i \mathbb{E}_{\theta} x_i$$

if $P_{\theta} = \text{uniform}$ $SKL(P_{\theta}, \text{uniform}) = 0$

If $TV(P_{\theta}, U) > \varepsilon \rightarrow SKL(P_{\theta}, U) > 4\varepsilon^2$

$$\rightarrow \exists i, j \text{ s.t. } \mathbb{E}_{\theta} x_i x_j > \frac{4\varepsilon^2}{n^2}$$

$$\text{or } \exists i \text{ s.t. } \mathbb{E}_{\theta} x_i > \frac{4\varepsilon^2}{n}$$

completing proof is left as exercise \square